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Development of E-ACTIVETRANS for Young Professional Planners/Engineers

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ABSTRACT

This paper presents a development of an expert system to be used as an advisory in finding the solution to problems which are normally solved by human experts. The E-ACTIVETRANS is developed to help young engineers/planners in designing a new cycle lane in urban areas and also to help in reallocation of an existing roadway space for cycle lanes. This system has three sub-systems: Planning on Strategies to Shift from Passive Transportation to Active Transportation, Design on Bicycle Facilities and Examples of Successful Implementation. This paper focuses on the design of bicycle facilities whereby the prototype was developed based on data acquired from the domain experts who are involved in bicycle facility module design, as well as the initial text analysis obtained during the domain familiarisation stage. The validation of the system was performed through a comparison of knowledge content in E-ACTIVETRANS based on expert opinion. The average level of acceptance is 91 percent which validates the system and knowledge of the experts.

Keywords: Bicycle facilities, E-ACTIVETRANS, expert system, human experts

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INTRODUCTION

E-ACTIVETRANS is developed as an advisory system to provide guidance to users on solutions to problems which are normally solved by experts (Forslund, 1995). Both expert and advisory systems play the role of problem-solving packages that mimic experts (Mansyur, 2011). E-ACTIVETRANS was developed using knowledge from experts in the transportation field, and information obtained from guidelines, encyclopaedia and research publications.

DEVELOPMENT OF E-ACTIVETRANS

The E-ACTIVETRANS is developed using Visual Basic.NET and MY SQL. VB is an event language designed to interact with the user on a running system. The most widely used type of representation consists of collection of facts, while rules are used to represent IF-THEN reasoning. These rules have the form of "IF 'condition' THEN 'action'." According to Pauziah et al. (2009), if the condition part is true within the scope of the knowledge base, then the condition would store the facts portion of the system knowledge engine. Therefore, the condition part is performed.

The E-ACTIVETRANS begins by outlining some key guiding principles to help in the selection and identification of available types of bicycle facilities. This guide classifies bicycle facilities into four (4) types. There are no fast and hard rules in determining the most appropriate type of bicycle facility for a certain location (Mansyur, 2011b).

The knowledge extracted during the acquisition process is grouped together in 5 segments in this design module. For the development of knowledge modules, each module solves a specific aspect of the problem within the domain even though some inter-dependency exists between the component tasks. Figures 1, 2 and 3 show the flowchart for the development of E-ACTIVETRANS advisory system, beginning from the first step. This paper focuses on the design of bicycle facilities; it outlines TWO (2) suggestions based on the new design of cycle lane and reallocation of roadway space.

New Design for Cycle Lane

There are several types of cycle lane in E-ACTIVETRANS. Choice is influenced by the vision of the route itself and the surrounding area in the context of delivering travel patterns. In this module, the user needs to know how to select the density area, type of user and other factors influencing the selection of bicycle facilities (VTPI, 2012). The E-ACTIVETRANS will advise the user on how to design the cycle lane according to the flowchart shown Figure 1.



Figure 1. Advisory expert system for new design for cycle lane

Reallocation of Road Way Space

This section describes how roadway design practices can encourage development of more efficient transportation system through reallocation of road space, such as shifting the road space from automobile traffic to other active transport modes such as bike lanes and sidewalks. Reallocation of roadway is particularly appropriate on congested streets (VTPI, 2014). The knowledge extracted during the knowledge acquisition process is grouped together into specific modules based on the objective of the users. Figure 2 and Figure 3 show the flowchart for the development of the reallocation of the existing roadway space for cycle lane's diagnostic from the first step.



Figure 2. Advisory expert system for the reallocation of roadway space for cycle lane



Figure 3. Advisory expert system for the reallocation of roadway space for cycle lane (continued)

Tał Nui	sle 1 mber of rules used in the E-ACTIV	ETRANS				
Sij	ıgle Rules			Conclus	ion (THEN-Pa	art)
Z	Condition (IF-Part					
	If there is any existing curb to curb minimum travel lanes	width where	cycle lane will fit while maintaining 3	.5m Restripe (with a v	inner lanes to vider curb lan	o provide a bike lane or a shared lane (e)
2	If one travel lane can be removed to of Service (LOS)	stripe cycle	lane and still maintain the acceptable	Level Remove	the travel lan	e to add a bike lane
Tw	vo Combined Rules					
Z	Master Rules	Condition (IF-Part) Operator	Sub-Rule	Conclus (THEN.	ion -Part)	
m	If there is no one travel lane can be removed to stripe the cycle lane and cannot maintain an acceptable Level of Service (LOS)	AND	If an alternative stripping configure replaces some of the lost capaci example: convert a 4-lane undivide to 2-lane + two way left, turn lane).	uration Remove ty (for ed road	the travel lan	e to add a bike lane
4	If there is an adequate right-of- way (ROW) to widen streets for bike lanes	AND	If there are no other constraints s mature trees within 1.5m of the e curb or edge of roadway	such as Widen to xisting	o provide bike	e lanes/shared lane (wide curb lane)
2	If there is no adequate right-of- way (ROW) to widen streets for bike lanes	AND	If right-of-way (ROW) is Wide acquired shared	n to provide bil d lane (wide curb	ke lanes/ lane)	
Πh	ree Combine Rules					
Ŭ	indition (IF-Part)				L)	[HEN-Part)
z	Master Rules	Operator	Sub-Rule Opera	ttor Sub-Rul	e C	onclusion
9	If there is no existing curb to curb width where cycle lane will fit while maintaining 3.5m minimum travel lanes	AND	If there are two or more AND travel lanes per direction	If ther existing than 3.5	e is an R lanewider la m	estripe the inner lanes to provide a bike une/shared lane (with wider curb lane)
	If there is a permit on street parking		If street have commercial frontage	If ther adequate parking	e is an P	rohibit on-street parking on one or both des & strip a bike lane
∞	If there is no permit on street parking		If street have residential frontage	There is occupan than 60%	a parking C cy greater to	onsider parking restrictions from 7am o 7 pm (Monday to Friday) to provide av time hike lane and evening parking

E-ACTIVETRANS REASONING VALIDATION

The reasoning rules of E-ACTIVETRANS were verified during system testing to ensure the validity of the system. A number of rules including the logical errors is summarized in Table 1.

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Development of E-ACTIVETRANS

E-ACTIVETRANS INTERFACE WINDOW

The prototype of E-ACTIVETRANS was developed according to the knowledge acquisition derived from the expert domains. The example of data output is shown in Figure 4.

E-ACTIVETRANS HOBLITY HANAGENERIT SCHEME EXPERT ADVISORY SYSTEM FOR ACTIVE TRANSPORT								
Welcome, bibie Logout								
PLANNING	DESIGN	SUCCESSFUL IMPLEM	ENTATION	E-LIBRARY	ABOUT			
This section describe how roadway design practices can encourage more efficient transportation by providing more space for walking and cycling.								
Road space is a scarce public resources. Conventional transport planning practices tend to devote road space to general traffic lanes. Here, reallocation of road space involves shifting road space from automobile traffic to other active transport modes; bike lanes and side valks. Reallocation of roadway is particularly appropriate on congestion roadways. To accommodate bicycle lanes, vide curb lanes or paved shoulders along roadways is reduced and narrowed where widening is impractical. This can be implemented when roadway capacity exceeds demand.								
Please answer the following question(s) to get your advise.								
1 Is there any existing such to such width where cycle lane will fit while								
1. Is there any existing cuto to club what where cycle and will in white maintaining 3.5 minimum travel lane? • YES * NO Inte						ith wider curb		
2. Are there two or more travel lanes per direction? ⊕ YES ⊖ NO								
3. Are existing la ⊕ YES ○ NO	ne wider than 3.5m?							

Figure 4. User interface for the decision of reallocation of roadway space

COMPARISON OF E-ACTIVETRANS RESULTS AND DOMAIN EXPERTS

The system validation was performed through a comparison of knowledge contained in E-ACTIVETRANS with the opinion of FOUR (4) domain experts as shown in Table 2.

Module	EXP 1	EXP 2	EXP 3	EXP 4
Module 1	88	100	93	98
Module 2	96	93	92	95
Module 3	93	90	96	87
Module 4	92	88	90	91
Module 5	82	84	90	88
Overall	90	91	92	92

 Table 1

 Evaluation of domain experts for knowledge contained in E-ACTIVETRANS

The overall acceptance levels of experts was 90%, 91%, 92% and 92%. Since an E-ACTIVETRANS is an abstraction of reality, perfect performance cannot be expected (O'Keefe, 1987).

CONCLUSION

This paper presented the development of how knowledge acquisition obtained from expert individuals in the transportation field as the expert domain which has been arranged accordingly with references obtained from guidelines, encyclopaedia and research publications to form the expert system. The level of acceptance was 90%, 91%, 92% and 92% shows that the system is validated and represents the knowledge of experts. Hence, the overall comments, the validation and evaluation results indicated that E-ACTIVETRANS system has a degree of user-friendliness acceptable for most intended users.

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